Dynamic Programming

"Those who cannot remember the past are condemned to repeat it."

— Jorge Agustín Nicolás Ruiz de Santayana y Borrás,

Admin

- Assignment 3 back
- Some common issues with greedy/exchange arguments
- "Greedy worksheet" linked to on course webpage
- We'll go over greedy again in midterm review

Student solutions!

- PDF on **glow** containing student solutions to some assignment problems
- Idea: give you an idea of how non-polished proofs might look
- (No promises of perfect correctness, or ideal length, or everything being explained)
- Don't distribute

Assignments

- Assignment 5 due Saturday
- Make sure to keep up with assignments!
 - Midterm soon
 - Weighted heavily
 - Much better to let me know beforehand if there's an issue

Midterm review

- Next Monday evening
- (Any questions/comments about that time?)
- All remote
- I'll send around a survey about when people can make it
- You can send in questions if you can't attend
- Will post a recording

Apply to be a TA!

- Application form on dept website
- Fun, educational
- OK if remote (need to live in US)



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Slow Recursion: Fibonnacci

- This naive recurrence is horribly slow
- Let T(n) denote the # of recursive calls
 - T(n) = T(n-1) + T(n-2) + 1
 - Can we lower bound this?

```
\frac{\text{RecFibo}(n):}{\text{if } n = 0}
return 0
else if n = 1
return 1
else
return RecFibo(n - 1) + \text{RecFibo}(n - 2)
```

Slow Recursion: Fibonnacci

- Correct answer:
- $T(n) \ge F_n$ for all $n \ge 1$

•
$$F_n \ge \phi^{n-2}$$
 where $\phi = \left(\frac{1+\sqrt{5}}{2}\right) \approx 1.6^{n-2}$ (exponential!)

$$\frac{\text{RecFibo}(n):}{\text{if } n = 0}$$
return 0
else if $n = 1$
return 1
else
return RecFibo $(n - 1) + \text{RecFibo}(n - 2)$

Memo(r)ization

- Recursive Fibonacci algorithm is slow because it computes the same functions over and over
- Can speed it up considerably by writing down the results of our recursive calls, and looking them up when we need them later



Dynamic Programming: Smart Recursion

- Dynamic programming is all about smart recursion by using memoization
- Here it cuts down on all useless recursive calls



Memoization

- Memoization: technique to store expensive function calls so that they can be looked up later
- (Avoids calling the expensive function multiple times)
- A core concept of dynamic programming, but also used elsewhere

Memoizing Fibonacci

- Write each entry down in an array when you compute it
- How do we compute the *n*th Fibonacci number?
 - Fill in the first two Fibonacci numbers.
 - Use those to fill in the third, then fourth, etc.
 - Takes O(1) to fill in a table entry
 - O(n) overall

A = 1 | 1 | 2 | 3 | 5 | 8 | 13 | 21

Dynamic Programming

• Formalized by Richard Bellman in the 1950s

We had a very interesting gentleman in Washington named Wilson. He was secretary of Defense, and he actually had a pathological fear and hatred of the word "*research*". I'm not using the term lightly; I'm using it precisely. His face would suffuse, he would turn red, and he would get violent if people used the term "*research*" in his presence. You can imagine how he felt, then, about the term "*mathematical*"....I felt I had to do something to shield Wilson and the Air Force from the fact that I was really doing mathematics inside the RAND Corporation. What title, what name, could I choose?

• Chose the name "dynamic programming" to hide the mathematical nature of the work from military bosses

Recipe for a Dynamic Program

- Formulate the right subproblem. The subproblem must have an optimal substructure
- Formulate the recurrence. Identify how the result of the smaller subproblems can lead to that of a larger subproblem
- State the base case(s). The subproblem thats so small we know the answer to it!
- State the final answer. (In terms of the subproblem)
- Choose a memoization data structure. Where are you going to store already computed results? (Usually a table)
- Identify evaluation order. Identify the dependencies: which subproblems depend on which ones? Using these dependencies, identify an evaluation order
- Analyze space and running time. As always!

Weighted Scheduling

- **Input.** Given *n* intervals labeled 1, ..., n with starting and finishing times $(s_1, f_1), ..., (s_n, f_n)$ and each interval has a non-negative value or weight v_i
- **Output.** We must select non-overlapping intervals with the maximum weight. That is, output $I \subseteq \{1, ..., n\}$ that are pairwise non-overlapping that maximize $\sum_{i \in I} v_i$
- **Optimal cost.** Can we just find the value of the best solution? Find the largest $\sum_{i \in I} v_i$ where intervals in *I* are compatible.
- Let Opt-Schedule(n) be the value of the optimal schedule

Remember Greedy?

- Greedy algorithm earliest-finish-time first
 - Considers jobs in order of finish times
 - Greedily picks jobs that are non-overlapping
- We proved greedy is optimal when all weights are one
- How about the weighted interval scheduling problem?



Helpful Information

- Suppose the intervals are sorted by finish times
- Let p(j) be the predecessors of j that is, largest index i < j such that intervals i and j are not overlapping
- Define p(j) = 0 if all intervals i < j overlap with j



Helpful Information

• Let p(j) be the predecessors of j that is, largest index i < j such that intervals i and j are not overlapping

•
$$p(8) = ?$$
, $p(7) = ?$, $p(2) = ?$



Helpful Information

• Let p(j) be the predecessors of j that is, largest index i < j such that intervals i and j are not overlapping

•
$$p(8) = 1$$
, $p(7) = 3$, $p(2) = 0$



Subproblem for our DP

• Subproblem.

- For $1 \le i \le n$, let Opt-Schedule(*i*) be the value of the optimal schedule that only uses intervals $\{1, ..., i\}$
- Notice the optimal substructure
- Figuring out how we can build from smaller subproblems
- Let us consider the last interval i with (s_i, t_i)
 - **Case 1.** Interval *i* is not in the optimal solution, then Opt-Schedule(i) = Opt-Schedule(i 1)
 - **Case 2.** Interval i is in the optimal solution
 - No two intervals in the schedule can overlap: cannot have j < i such that $s_i \leq f_j$
 - Only intervals $j \leq p(i)$ can be in the same schedule as i

Recurrence for our DP

• Subproblem.

- For $1 \le i \le n$, let Opt-Schedule(*i*) be the value of the optimal schedule that only uses intervals $\{1, ..., i\}$
- Notice the optimal substructure
- **Recurrence.** Going from one subproblem to the next
 - Opt-Schedule(i) = $\max{\text{Opt-Schedule}(i-1), v_i + \text{Opt-Schedule}(p(i))}$
- Base case.
 - Opt-Scheduler(0) = 0 (no intervals to schedule)
- Correctness
 - Using induction based on the recurrence

Finding p(i)

- Can do a linear scan in O(i) time
- Or: we have the intervals in sorted order by finishing time. Binary search for s_i (the start time of i) in this list
 - Finds the largest interval j with $f_j \leq s_i$
 - Then p(i) = j
 - Time is $O(\log i) = O(\log n)$

Running Time?

- How many subproblems do we need to solve?
 - *O*(*n*)
- How long does it take to solve a subproblem?
 - O(1) to take the max
 - $O(\log n)$ to find p(i)
- Do we need to do any preprocessing?
 - Need to sort; $O(n \log n)$
- Overall running time: $O(n \log n)$

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Recursive Solution?

Suppose for now that we do not memoize: just a divide and conquer recursion approach to the problem.

Opt-Schedule(i):

- If j = 0, return 0
- Else
 - Return max(Opt-Schedule $(j 1), v_j + Opt-Schedule(p(j)))$
- How many recursive calls in the worst case?
 - Depends on p(i)
- Can we create a bad instance?

Recursive Solution: Exponential

- For this example, asymptotically how many recursive calls?
- Grows like the Fibonacci sequence: exponential time!
- Lots of redundancy!
 - How many distinct subproblems are there to solve?
 - Opt-Schedule(*i*) for $1 \le i \le n+1$



Dynamic Programming Tips

- Recurrence/subproblem is the key!
 - DP is a lot like divide and conquer, while writing extra things down
 - When coming to a new problem, ask yourself what subproblems may be useful? How can you break that subproblem into smaller subproblems?
 - Be clear while writing the subproblem and recurrence!
- In DP we usually keep track of the *cost* of a solution, rather than the solution itself

Acknowledgments

- Some of the material in these slides are taken from
 - Kleinberg Tardos Slides by Kevin Wayne (<u>https://www.cs.princeton.edu/~wayne/kleinberg-tardos/pdf/04GreedyAlgorithmsl.pdf</u>)
 - Jeff Erickson's Algorithms Book (<u>http://jeffe.cs.illinois.edu/</u> <u>teaching/algorithms/book/Algorithms-JeffE.pdf</u>)