CSCI 136 Data Structures & Advanced Programming

> Lecture 26 Spring 2020 Profs Bill & Dan

### Last Time

- Heaps
  - Implementation details
    - Data stored in an implicit binary tree in a Vector
  - Code inspection (structure5.VectorHeap)
  - Big-O of key operations

# Today

- Heaps (again!)
  - Finish Implementation details
  - Some analysis + proofs
- Heapsort

# Implementing Heaps: Recap

- Strategy: perform tree modifications that always preserve tree *completeness*, but may violate heap property. Then fix.
  - Add/remove never add gaps to array
    - We always add in next available array slot (left-most available spot in binary tree)
    - We always remove using "final" leaf
  - When elements are added and removed, do small amount of work to "re-heapify"
    - pushDownRoot(): recursively swaps large element down the tree
    - percolateUp(): recursively swaps small element up the tree

# VectorHeap Summary

- Get is O(1), add/remove are both O(log n)
- Data is not completely sorted
  - A "partial" ordering is maintained for all root-toleaf paths
- Note: VectorHeap(Vector<E> v)
  - Takes an unordered Vector and uses it to construct a heap
  - How?

# Heapifying A Vector (or array)

Problem: You are given a Vector V that is not a valid heap, and you want to "heapify" V

- Method I: Top-Down
  - Assume V[0...k] satisfies the heap property
  - Call percolateUp on item in location k+1
  - Now, V[0..k+1] satisfies the heap property



Grow valid heap region one element at a time

#### **Practice Top-Down**

#### Input:

- int a[6] =  $\{7,5,9,1,2,5,4\}$ 0 1 2 3 4 5 6
  - for (int i = 0; i < a.length; i++)
    percolateUp(a, i);</pre>

Result: a is a valid heap!

• a =  $\begin{bmatrix} 1 & | & 2 & | & 4 & | & 7 & | & 5 & | & 9 & | & 5 \end{bmatrix}$ 0 1 2 3 4 5 6

# Heapifying A Vector (or array)

Problem: You are given a Vector V that is not a valid heap, and you want to "heapify" V

- Method II: Bottom-up
  - Assume V[k..n] satisfies the heap property
  - Now call pushDown on item in location k-I
  - Then V[k-1..n] satisfies heap property



#### Practice Bottom-Up

#### Input:

- int a[6] =  $\{7,5,9,1,2,5,4\}$ 0 1 2 3 4 5 6
  - for (int i = a.length-1; i > 0; i--)
     pushDownRoot(a, i);

Result: a is a valid heap!

• a =  $\begin{bmatrix} 1 & | & 2 & | & 4 & | & 5 & | & 7 & | & 5 & | & 9 \end{bmatrix}$ 0 1 2 3 4 5 6

### Let's Compare

- Which is faster: Top down or Bottom Up?
  - Q: Think about a complete binary tree. Where do most of the nodes live?
  - A: The leaves!
  - Given that most of the nodes are leaves, should we percolateUp or pushDown?
    - To answer this, we should think about "how far" we need to move a node in the worst case.

#### Some Sums (for your toolbox)

$$\sum_{d=0}^{d=k} 2^d = 2^{k+1} - 1$$

$$\sum_{d=0}^{d=k} r^d = (r^{k+1} - 1) / (r - 1)$$

$$\implies \sum_{d=1}^{d=k} d * 2^d = (k-1) * 2^{k+1} + 2$$

$$\implies \sum_{d=1}^{d=k} (k-d) * 2^d = 2^{k+1} - k - 2$$

All of these can be proven by (weak) induction.

Try these proofs to hone your skills!

The second sum is called a geometric series. It works for any r≠0

### Top-Down vs Bottom-Up

- **Top-down heapify (percolate up)**: elements at depth d may be swapped d times.
- The total # of swaps is:

(recall: h = log n)  $\sum_{d=1}^{h} d2^{d} = (h-1)2^{h+1} = (\log n - 1)2n + 2$ 

- This is  $O(n \log_2 n)$
- Some intuition: most of the elements are in the lowest levels of the tree, so each of them might have to move to root: O(log<sub>2</sub>n) swaps per element

#### Top-Down vs Bottom-Up

- Bottom-up heapify (push down): elements at depth d may be swapped h-d times.
- The total # of swaps is:

$$\sum_{d=1}^{h} (h-d)2^d = 2^{h+1} - h - 2 = 2n - \log n + 2$$

- This is O(n) it beats top-down!
- Some intuition: most of the elements are in the lowest levels of the tree, so each of them will only be pushed down (swapped) a small number of times
   SO COOL !!!

# HeapSort

- Kind of an "Advanced" version of Selection Sort
- Strategy:
  - I. Make a *max-heap*: array[0...n]
    - array[0] is largest value
    - array[n] is rightmost leaf
  - 2. Take the largest value (array[0]) and swap it with the rightmost leaf (array[n])
  - 3. Call pushDownRoot on array[0...n-1]
    - Now our "heap" is one element smaller, and the largest element is at end of array.

Repeat until heap is empty and array is sorted

# HeapSort

- Another O(n log n) sort method
- Heapsort is not stable
  - The relative ordering of elements is not preserved in the final sort
    - Why not?
      - There are multiple valid heaps given the same data
- Heapsort can be done *in-place* 
  - No extra memory required!!!
  - Great for resource-constrained environments

#### Heap Sort vs QuickSort



# Why Heapsort?

- Heapsort is slower than Quicksort in general
- Any benefits to heapsort?
  - *Guaranteed* O(n log n) runtime
- Works well on mostly sorted data, unlike quicksort
- Good for incremental sorting

## More on Heaps

- Set-up: We want to build a *large* heap. We have several processors available.
- We'd like to use them to build smaller heaps and then merge them together
- Suppose we can share the array holding the elements among the processors.
  - How long to merge two heaps?
  - How complicated is it?
- What if we use BinaryTrees for our heaps?

# Mergeable Heaps

- We now want to support the additional destructive operation merge(heap1, heap2)
- Basic idea: the heap with larger root somehow points into heap with smaller root
- Challenges
  - Points how? Where?
  - How much reheapifying is needed
  - How deep do trees get after many merges?

## Skew Heap

- Heaps are not *necessarily* complete BTs
  - We made this requirement to guarantee performance in our VectorHeap representation
  - Rather than use Vector as underlying data structure, we can use a binary tree!
- Details are in the book, but at a high level...
  - The merge algorithm keeps the tree shallow over time
  - Theorem: Any set of m SkewHeap operations can be performed in O(m log n) time, where n is the total number of items in the SkewHeaps

### Skew Heap: Merge Pseudocode

SkewHeap merge(SkewHeap S, SkewHeap T) if either S or T is empty, return the other Case 1 if T.minValue < S.minValue swap S and T (S now has minValue) if S has no left subtree, T becomes its left subtree case 2 else

> let temp point to right subtree of S left subtree of S becomes right subtree of S merge(temp, T) becomes left subtree of S Case 3 return S

## Skew Heap: Merge Examples







*Bailey* page 331

# **Tree Summary**

- Trees
  - Express hierarchical relationships
  - Level ordering captures the relationship
    - i.e., ancestry, game boards, decisions, etc.
- Heap
  - Partially ordered tree based on item priority
  - Node invariants: parent has higher priority than each child
  - Provides efficient PriorityQueue implementation