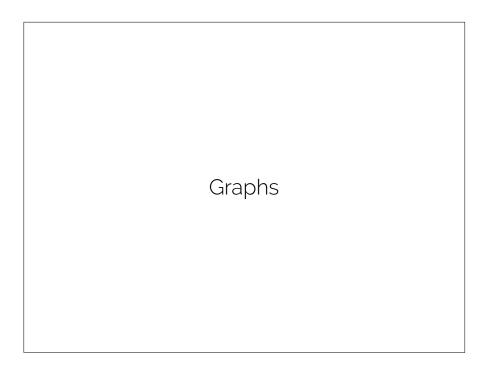
CSCI 136: Data Structures and Advanced Programming Lecture 26 Graphs, part 1

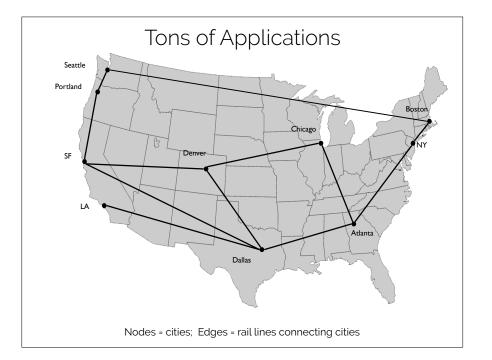
Instructor: Dan Barowy

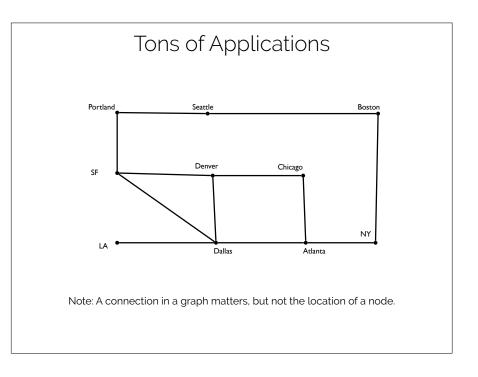
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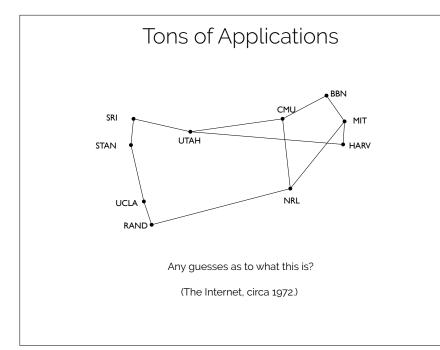
Outline	
Graph definitions	

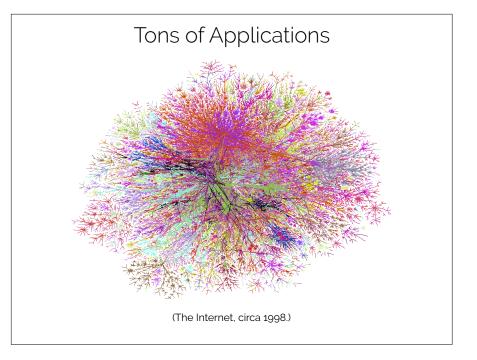


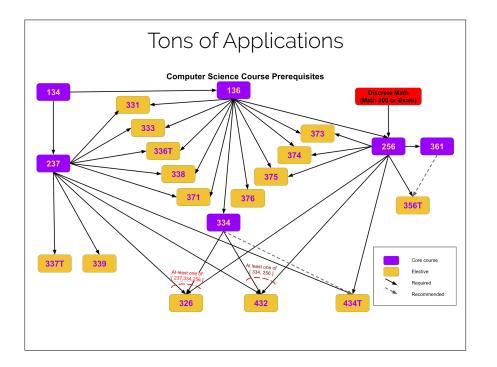


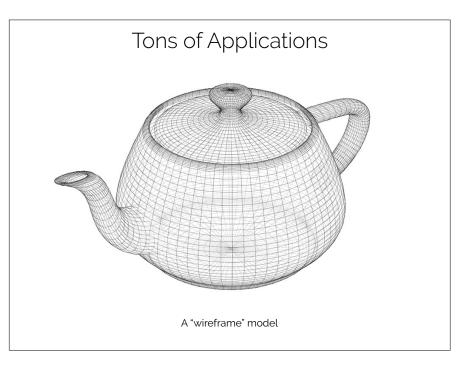












Undirected graph

An **undirected graph G** is an abstract data type that consists of two sets:

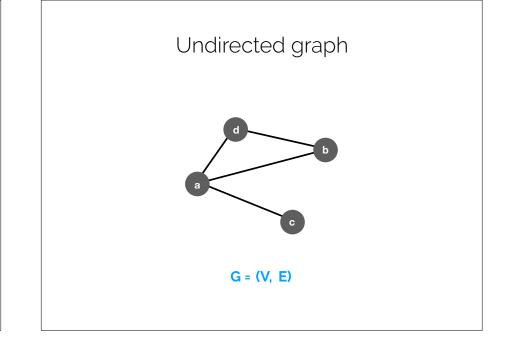
- a set V of vertices (or nodes), and
- a set **E** of **undirected edges**.

A graph can be used to represent any structure in which pairs of elements are, in some sense, "related."

In an undirected graph, data can be associated either with a vertex, an edge, or both.

Example: vertex data = city; edge data = distance.

Undirected edges make sense here because the distance from Williamstown to Boston is the same as the distance from Boston to Williamstown.



Directed graph

A **directed graph G** is an abstract data type that consists of two sets:

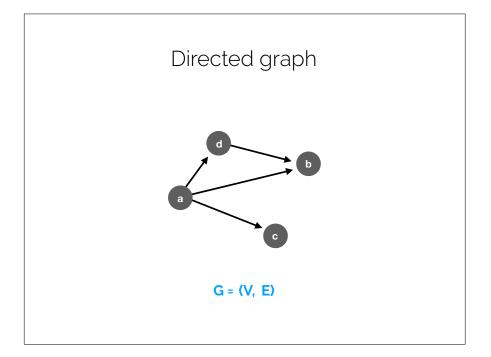
- a set **V** of **vertices** (or **nodes**), and
- a set **E** of **directed edges**.

A directed graph can be used to represent any structure in which pairs of elements are "one-way related."

In a directed graph, data can be associated either with a vertex, an edge, or both.

Example: vertex data = people; edge data = "loves".

Directed edges make sense here because... unrequited love. See (countless) examples from popular culture.



Walking a graph

A walk from u to v in a graph G = (V, E) is an alternating sequence of vertices and edges

 $\label{eq:constraint} \begin{array}{l} u = v_{_0}, \; e_{_1}, \; v_{_1}, \; e_{_2}, \; v_{_2}, \; \ldots \; , \; v_{_{k-1}}, \; e_{_k}, \; v_{_k} = v \\ \text{such that } e_{_i} \; = \; \{v_{_i} \; , \; v_{_{i+1}}\} \; \text{for i} \; = \; 1, \; \ldots \; , \; k \end{array}$

- A walk starts and ends with a vertex.
- A walk can travel over any edge and any vertex any number of times.
- If no edge appears more than once, the walk is a path.
- If no vertex appears more than once, the walk is a simple path.

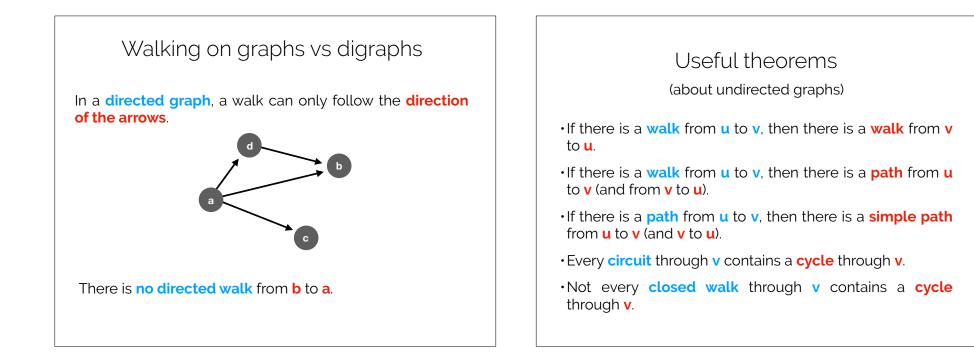
Walking in circles

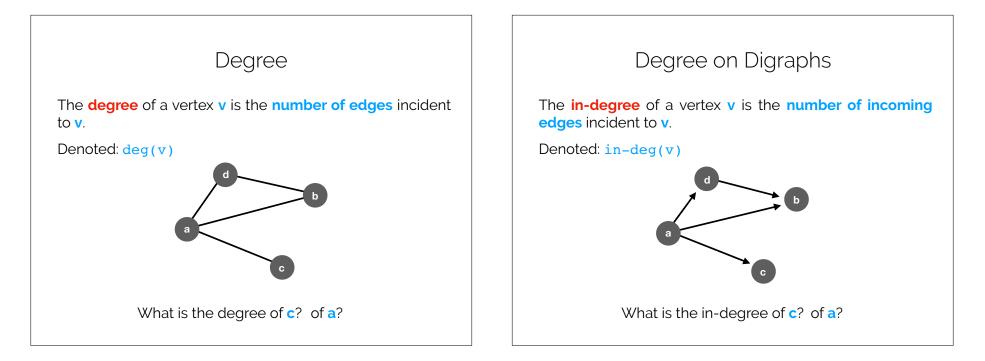
A closed walk in a graph G = (V, E) is a walk

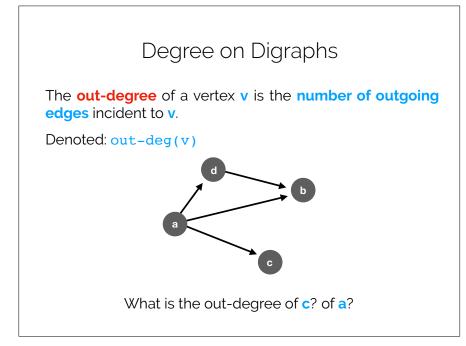
 $v_{_0},\ e_{_1},\ v_{_1},\ e_{_2},\ v_{_2},\ \ldots$, $v_{_{k-1}},\ e_{_k},\ v_{_k}$ such that each $v_{_0}\ =\ v_{_k}$

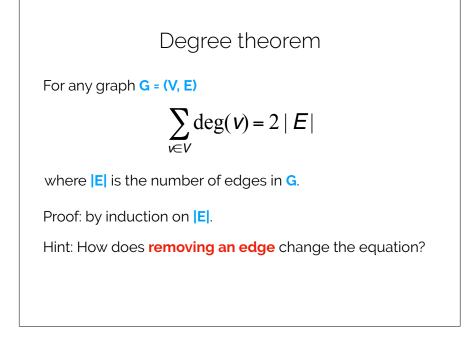
• A circuit is a path where $v_0 = v_k$ (no repeated edges)

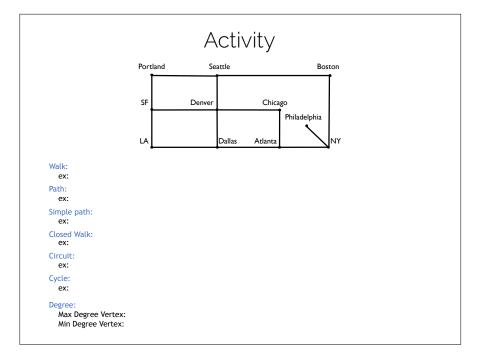
- A cycle is a simple path where $v_0 = v_k$ (no repeated vertices except v_0)
- •The **length** of a walk is the number of edges in the sequence.

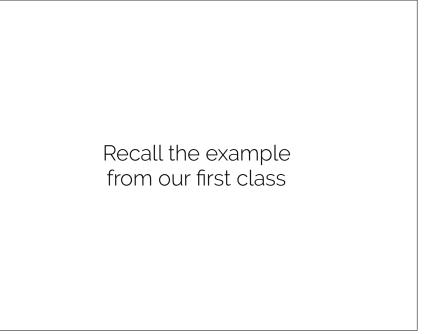




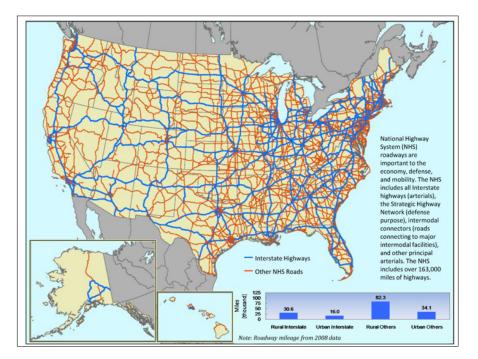


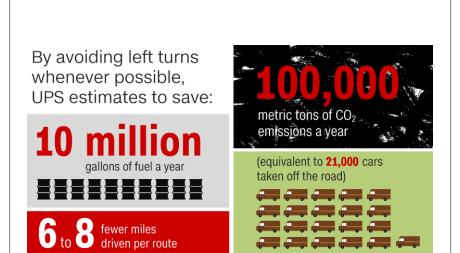












Source: UPS estimates for 2016, related to the deployment of the ORION routing system on US routes

A study on crash factors in intersection-related accidents from the US National Highway Traffic Safety Association shows that turning left is one of the leading "critical pre-crash events" ... About 61 percent of crashes that occur while turning or crossing an intersection involve left turns, as opposed to just 3.1 percent involving right turns.

source: <u>cnn.com</u>

Finding Shortest Paths

Data: road segments

road segment: (source, destination, length)

Input: source, destination

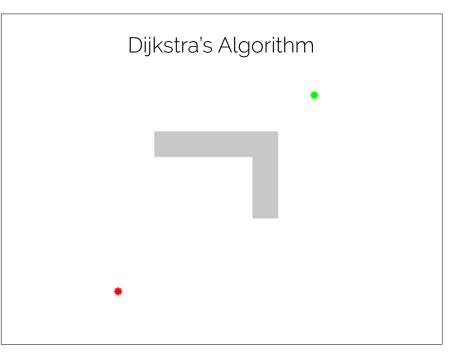
Output: shortest path

path: (segment1, ..., segmentn)

The Algorithm: Dijkstra's Algorithm

Data structures:

graph: essential representation of a "road network" priority queue: ordered set of next roads to try also uses: lists, arrays, stacks, ...



Recap & Next Class

Today we learned:

Graph definitions

Next class:

Graph ADT operations

Graph representations

Interesting graph problems