

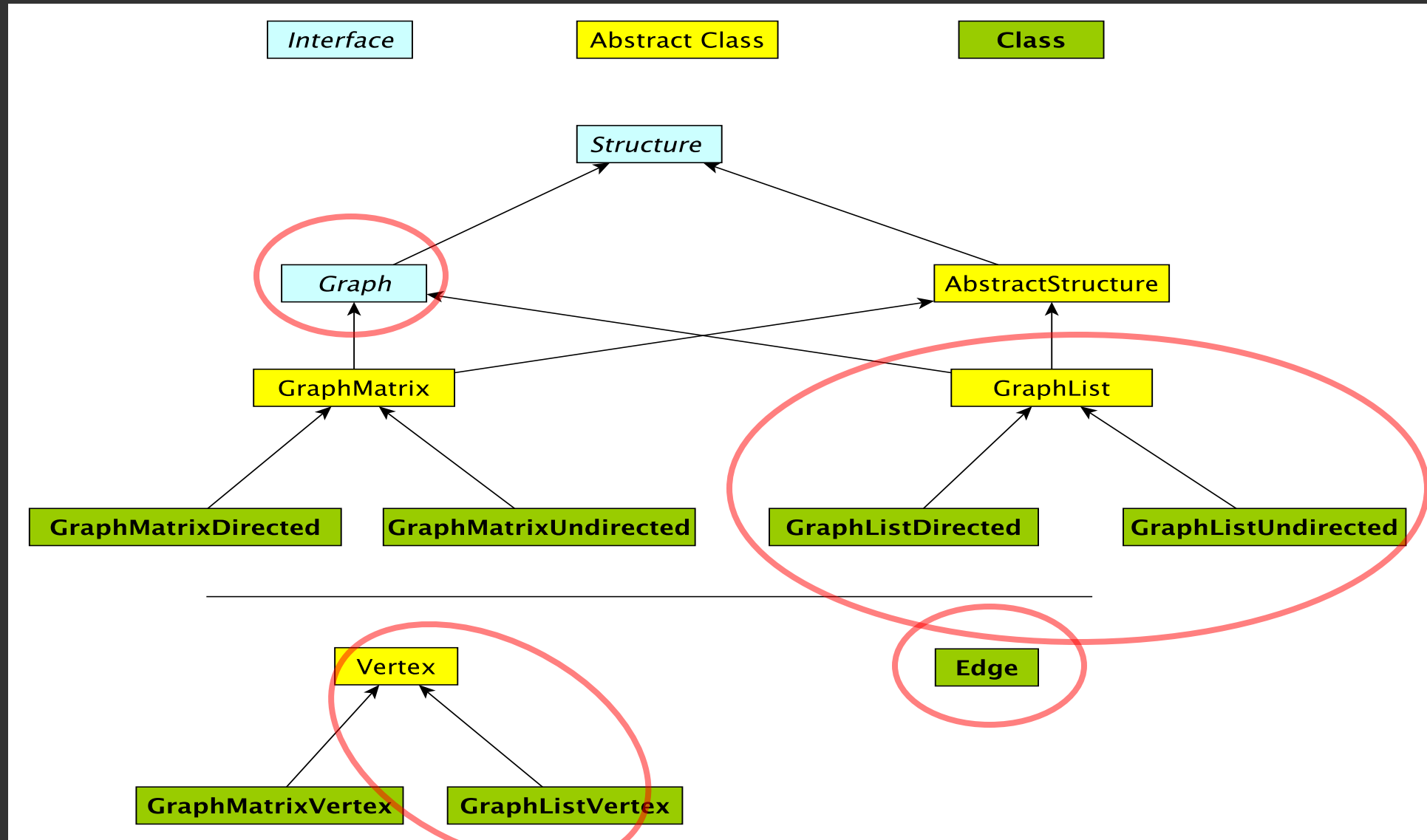
CSCI 136
Data Structures &
Advanced Programming

Implementing Graphs:
Adjacency Lists

Video Outline

- Graph Implementation Details
 - Adjacency Matrix – covered in another video
 - Adjacency List – covered in this video
- Time/Space Complexity

Graph Classes in structure5



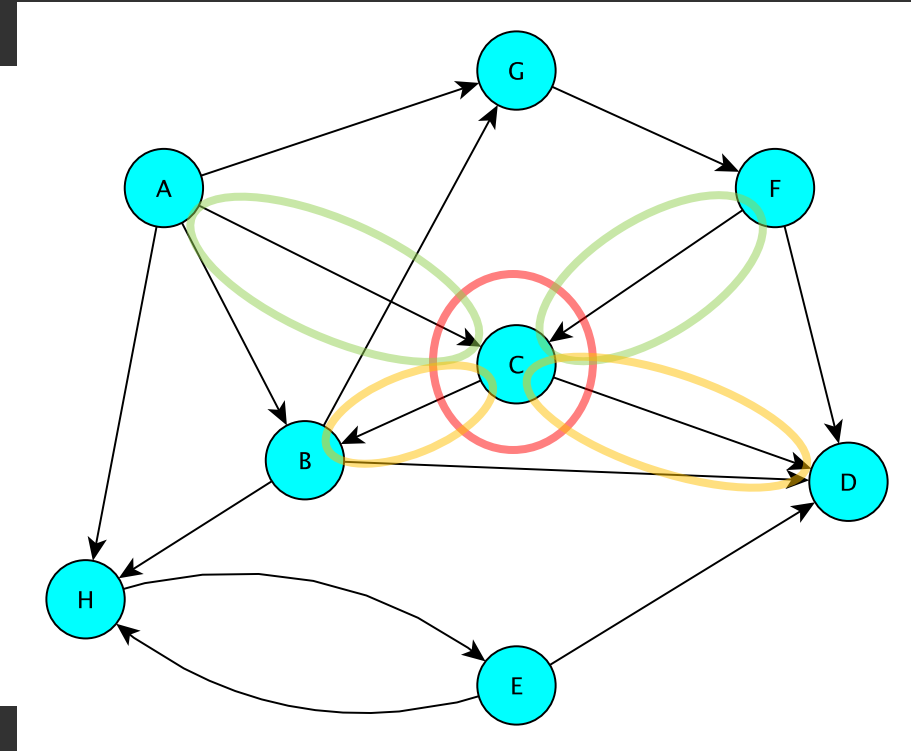
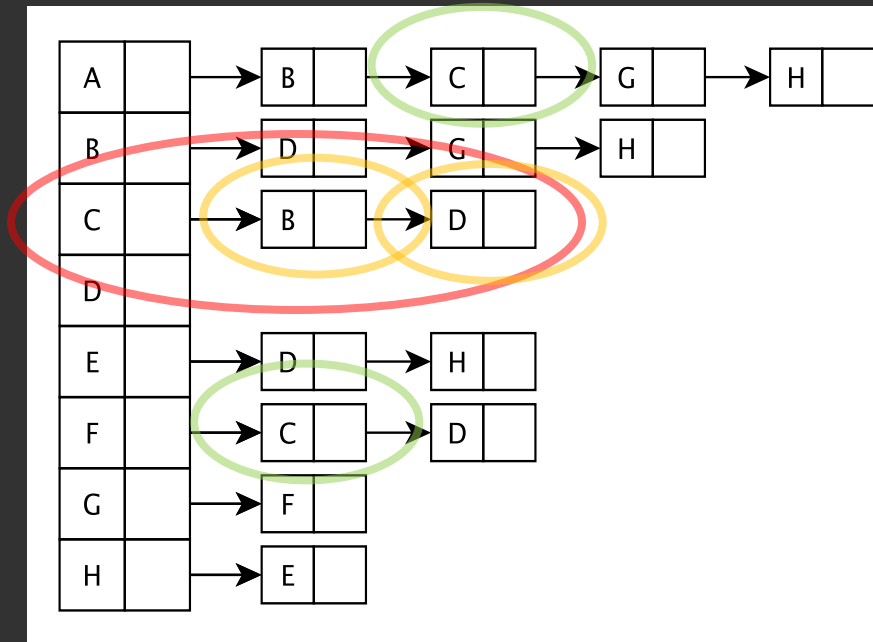
GraphList: Big Picture

- Matrix representation wastes space storing non-edges
- Maintain an *adjacency list* of *edges* at each vertex (no adjacency matrix)
 - Keep only *outgoing* edges for directed graphs
- Support both directed and undirected graphs
 - Abstract `GraphList` implements common functionality
 - Concrete classes `GraphListDirected` and `GraphListUndirected` complete implementation

GraphList

- Want to store edges adjacent to each vertex
- Let's just store a List of them
 - specifically, a SinglyLinkedList
- If we do that for all vertices, then we've stored the whole graph!

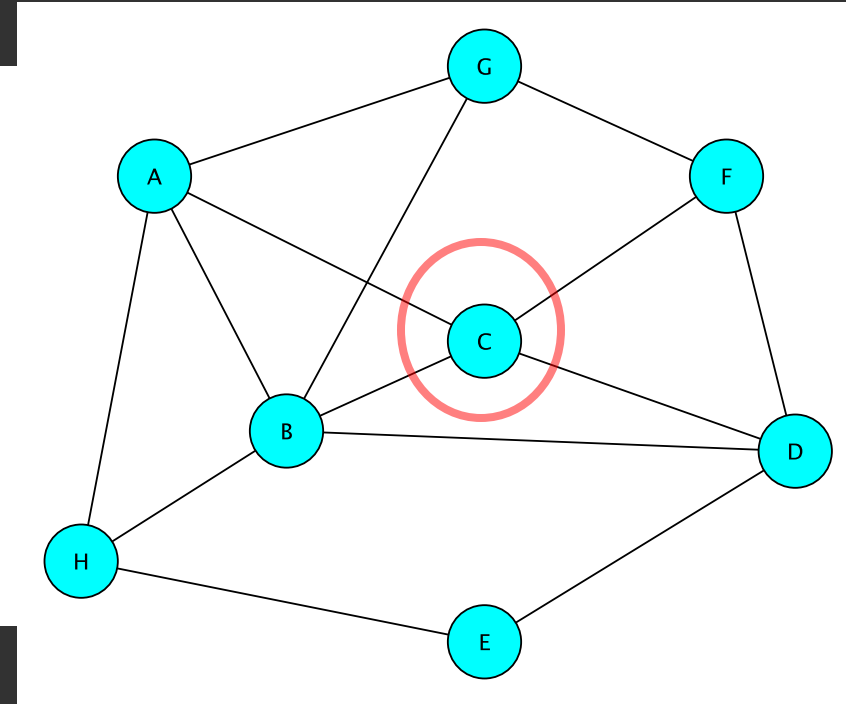
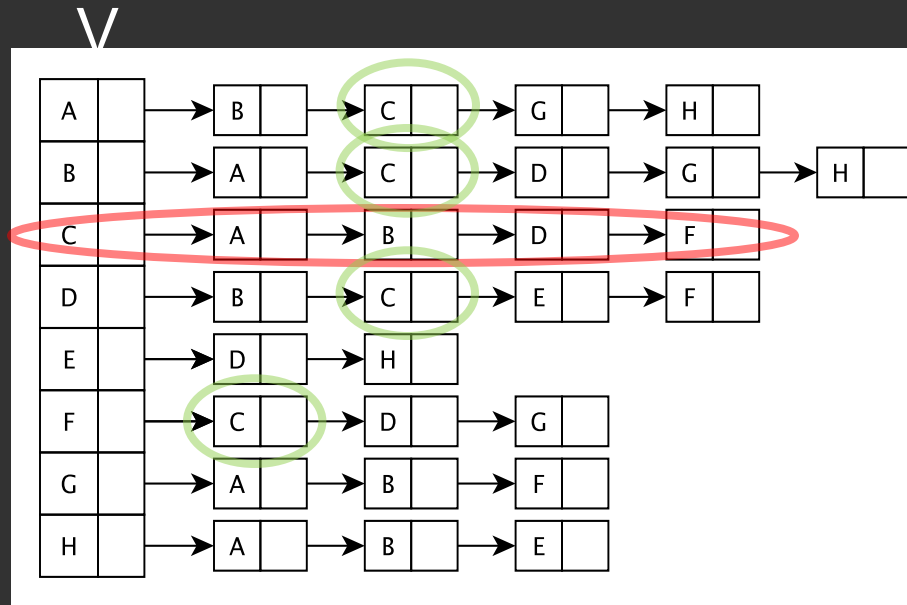
Adjacency List : Directed Graph



The vertices are stored in a $\text{Map}\langle V, \text{GraphListVertex}\rangle$

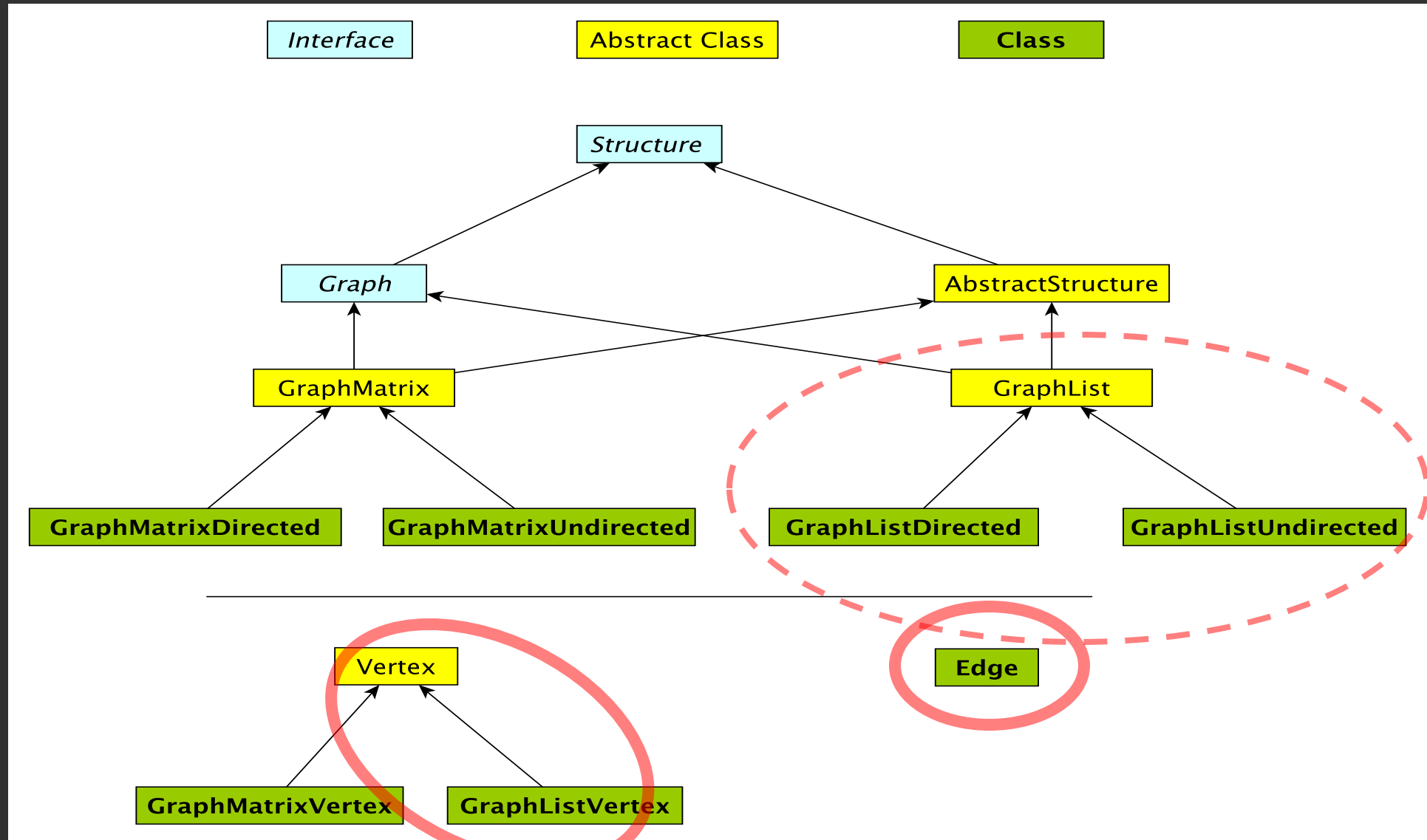
Each GraphListVertex contains a linked list of all edges with a given **source**

Adjacency List : Undirected Graph



The vertices are stored in a `Map<V, GraphListVertex>`
Each `GraphListVertex` contains a linked list of all edges
incident to a given vertex

Graph Classes in structure5



Vertex and GraphListVertex

- We use the same `Edge` class for all graph types, but we will **extend `Vertex` to include an `Edge` list**
- `GraphListVertex` class adds to `Vertex` class:
 - A Structure to store edges adjacent to the vertex
 - Several methods

```
public void addEdge(Edge<V,E> e)
public boolean containsEdge(Edge<V,E> e)
public Edge<V,E> removeEdge(Edge<V,E> e)
public Edge<V,E> getEdge(Edge<V,E> e)
public int degree()
// and methods to produce Iterators...
```

GraphListVertex

```
class GraphListVertex<V,E> extends Vertex<V>
{
    protected Structure<Edge<V,E>> adjacencies;
```

GraphListVertex (extends Vertex)

```
public GraphListVertex(V label){
    super(label); // init superclass' fields (Vertex)
    adjacencies = new SinglyLinkedList<Edge<V,E>>();
}

public boolean containsEdge(Edge<V,E> e){
    return adjacencies.contains(e);
}

public void addEdge(Edge<V,E> e){
    if (!containsEdge(e)) { // no duplicate edges
        adjacencies.add(e);
    }
}

public Edge<V,E> removeEdge(Edge<V,E> e) {
    return adjacencies.remove(e);
}
```

GraphListVertex Iterators

```
// Iterator for incident edges
public Iterator<Edge<V,E>> adjacentEdges() {
    return adjacencies.iterator(); // use SLL's iter
}

// Iterator for adjacent vertices
public Iterator<V> adjacentVertices() {
    ???
}
```

How can we iterate over the adjacent vertices?

Iterating over vertices

- Option 1: Store all the vertices in some list; return its iterator
 - Easy, but a bit fragile and space inefficient
- Option 2: Build class to iterate through edges one at a time using edge iterator; return vertex

We'll do Option 2 this time

GraphListVertex Iterators

Note the A in
GraphListAIterator

```
// Iterator for incident edges
public Iterator<Edge<V,E>> adjacentEdges() {
    return adjacencies.iterator(); // use SLL's iter
}

// Iterator for adjacent vertices
public Iterator<V> adjacentVertices() {
    return new GraphListAIterator<V,E>
        (adjacentEdges(), label());
}
```

GraphListAIterator creates an Iterator over *vertices* based on the Iterator over *edges* produced by adjacentEdges()

GraphListAlterator: Dispenses Neighboring Vertices

GraphListAlterator is a class with two instance variables:

```
protected Iterator<Edge<V,E>> edges;
protected V vertex;

public GraphListAlterator(Iterator<Edge<V,E>> i, V v) {
    edges = i;
    vertex = v;
}

public V next() {
    Edge<V,E> e = edges.next();
    if (vertex.equals(e.here())) {
        return e.there();
    } else { // could be an undirected edge!
        return e.here();
    }
}
```

GraphList (Abstract base class)

- To implement `GraphList`, what data structures do we need?
 - (Recall: We maintain an *adjacency list* of *edges* at each vertex)
- `GraphListVertex` class
 - Instance vars: `label`, `visited` flag, *linked list* of *edges*
- We do NOT need a free list like `GraphMatrix`
- We do NOT need to know $|V|$ ahead of time

GraphList

```
protected Map<V,GraphListVertex<V,E>> dict;
protected boolean directed;

protected GraphList(boolean dir){
    dict = new Hashtable<V,GraphListVertex<V,E>>();
    directed = dir;
}

public void add(V label) {
    if (dict.containsKey(label)) // unique vertices only
        return;

    GraphListVertex<V,E> v = new GraphListVertex<>(label);
    dict.put(label, v);
}
```

```
public Edge<V,E> getEdge(V labelA, V labelB) {  
    // Create "dummy edge" for searching (ignore value)  
    Edge<V,E> e = new Edge<>(get(labelA), get(labelB),  
        null, directed);  
    return dict.get(labelA).getEdge(e);  
}
```

(in GraphListVertex:)

```
public Edge<V,E> getEdge(Edge<V,E> e) {  
    // Go through all V's adjacent edges and compare  
    Iterator<Edge<V,E>> edges = adjacencies.iterator();  
    while (edges.hasNext()) {  
        Edge<V,E> adjE = edges.next();  
        if (e.equals(adjE))  
            return adjE;  
    }  
    return null;  
}
```

GraphListDirected

- `GraphListDirected/Undirected` implement any methods requiring different treatment due to directedness of edges
 - `addEdge`, `remove`, `removeEdge`, ...
 - edges appear in BOTH lists in undirected!
- We will only look at `GraphListDirected` in this video because the concepts are similar, and undirected version is slightly more straightforward

```
// in GraphListDirected.java

// first vertex is source, second is destination
public void addEdge(V vLabel1, V vLabel2, E label) {
    // first get the vertices
    GraphListVertex<V,E> v1 = dict.get(vLabel1);
    GraphListVertex<V,E> v2 = dict.get(vLabel2);

    // create the new edge
    Edge<V,E> e = new Edge<V,E>(v1.label(), v2.label(), label, true);

    // add edge only to source vertex linked list (aka adjacency list)
    v1.addEdge(e);
}
```

```
// in GraphListDirected.java

public V remove(V label) {
    //Get vertex out of map/dictionary
    GraphListVertex<V,E> v = dict.get(label);

    //Iterate over all vertex labels
    Iterator<V> vi = iterator();
    while (vi.hasNext()) {
        //Get next vertex label in iterator
        V v2 = vi.next();

        //Remove all edges to "label"
        //If edge does not exist, removeEdge returns null
        removeEdge(v2,label);
    }

    //Remove vertex from map
    dict.remove(label);
    return v.label();
}
```

```
// in GraphListDirected.java

public E removeEdge(V vLabel1, V vLabel2) {
    //Get vertices out of map
    GraphListVertex<V,E> v1 = dict.get(vLabel1);
    GraphListVertex<V,E> v2 = dict.get(vLabel2);

    //Create a "temporary" edge connecting two vertices
    Edge<V,E> e = new Edge<>(v1.label(), v2.label(), null, true);

    //Remove edge from source vertex linked list
    e = v1.removeEdge(e);

    if (e == null) {
        return null;
    } else {
        return e.label();
    }
}
```

GraphList: Big Picture

- Maintain an *adjacency list* of *edges* at each vertex (no adjacency matrix)
 - Keep only *outgoing* edges for directed graphs
- **Space:** we only “pay for what we store”
 - Vertex lists are as large as there are edges
- **Performance:** no “direct” way to access edges
 - We can quickly find a vertex, but need to scan through its unordered adjacency list

GraphList Efficiency

(assuming $O(1)$ Map operations)

For a `GraphListDirected<V, E>`

• where $|E|$ = number of edges, and $|V|$ = number of vertices

Operation	Big-O
<code>add(V label)</code>	$O(1)$
<code>remove(V label)</code>	$O(V + E)$
<code>addEdge(V v1, V v2)</code>	$O(\min(V , E))$
<code>getEdge(V v1, V v2)</code>	$O(\min(V , E))$
<code>removeEdge(V v1, V v2)</code>	$O(\min(V , E))$
Space Usage	$O(V + E)$

$O(\min(|V|, |E|))?$

- Why is `removeEdge` $O(\min(|V|, |E|))$?
 - We don't know which is smaller
 - For lots of graphs, $|V|$ is smaller
 - But not always! Some graphs have few edges
- To remove an edge, we must traverse all edges in a vertex's adjacency list.
 - There cannot be more than $|V|$ edges in the adjacency list
 - There cannot be more than $|E|$ edges in the adjacency list.