# CSCI 136 <br> Data Structures \& Advanced Programming 

Implementing Graphs:
Adjacency Lists

## Video Outline

- Graph Implementation Details
- Adjacency Matrix - covered in another video
- Adjacency List - covered in this video
- Time/Space Complexity


## Graph Classes in structure5

Interface
Abstract Class

## Class



## GraphList: Big Picture

- Maintain an adjacency list of edges at each vertex (no adjacency matrix)
- Keep only outgoing edges for directed graphs
- Support both directed and undirected graphs
- Abstract GraphList implements common functionality
- Concrete classes GraphListDirected and GraphListUndirected complete implementation


## Adjacency List : Directed Graph



The vertices are stored in an array V
$\mathrm{V}[\mathrm{i}]$ contains a linked list of all edges with a given source

## Adjacency List : Undirected Graph



The vertices are stored in an array V[]
$\mathrm{V}[\mathrm{i}]$ contains a linked list of all edges incident to a given vertex

## Graph Classes in structure5

Interface
Abstract Class

## Class



## Vertex and GraphListVertex

- We use the same Edge class for all graph types, but we will extend Vertex to include an Edge list
- GraphListVertex class adds to Vertex class:
- A Structure to store edges adjacent to the vertex
- Several methods

```
public void addEdge(Edge<V,E> e)
public boolean containsEdge(Edge<V,E> e)
public Edge<V,E> removeEdge(Edge<V,E> e)
public Edge<V,E> getEdge(Edge<V,E> e)
public int degree()
// and methods to produce Iterators...
```


## GraphListVertex (extends Vertex)

```
public GraphListVertex(V label){
    super(label); // init superclass' fields (Vertex)
    adjacencies = new SinglyLinkedList<Edge<V,E>>();
}
public boolean containsEdge(Edge<V,E> e) {
        return adjacencies.contains(e);
}
public void addEdge(Edge<V,E> e){
    if (!containsEdge(e)) { // no duplicate edges
            adjacencies.add(e);
    }
}
public Edge<V,E> removeEdge(Edge<V,E> e) {
    return adjacencies.remove(e);
```

\}

## GraphListVertex Iterators

```
// Iterator for incident edges
public Iterator<Edge<V,E>> adjacentEdges() {
    return adjacencies.iterator(); // use SLL's iter
}
// Iterator for adjacent vertices
public Iterator<v> adjacentVertices() {
        return new GraphListAIterator<V,E>
    (adjacentEdges(), label());
}
```

GraphListAIterator creates an Iterator over vertices based on the Iterator over edges produced by adjacentEdges ( )

# GraphListAlterator: Dispenses Neighboing Vertices 

GraphListAlterator is a class with two instance variables:

```
protected Iterator<Edge<V,E>> edges;
```

protected V vertex;
public GraphListAIterator(Iterator<Edge<V,E>> i, V v) \{
edges $=$ i;
vertex = v;
\}
public V next() \{
Edge<V,E> e = edges.next();
if (vertex.equals(e.here())) \{
return e.there();
\} else \{ // could be an undirected edge!
return e.here();
\}
\}

## GraphList (Abstract base class)

- To implement GraphList, what data structures do we need?
- (Recall: We maintain an adjacency list of edges at each vertex)
- GraphListVertex class
- Instance vars: label, visited flag, linked list of edges
- "Array V[]" of GraphListVertex
- Oops! We actually use a Map from $V$ to GraphListVertex: Map<V,GraphListVertex<V,E>> dict;
- We do NOT need a free list like GraphMatrix
- We do NOT need to know $|\mathrm{V}|$ ahead of time


## Graph Classes in structure5

Interface
Abstract Class
Class


## GraphList

```
protected Map<V,GraphListVertex<V,E>> dict;
protected boolean directed;
protected GraphList(boolean dir){
    dict = new Hashtable<V,GraphListVertex<V,E>>();
    directed = dir;
}
public void add(V label) {
    if (dict.containsKey(label)) // unique vertices only
        return;
    GraphListVertex<V,E> v = new GraphListVertex<>(label);
    dict.put(label, v);
```

\}
public Edge<V,E> getEdge(V labelA, V labelB) \{
// Create "dummy edge" for searching (ignore value)
Edge<V,E> e = new Edge<>(get(labelA), get(labelB), null, directed);
return dict.get(labelA).getEdge(e);
(in GraphListVertex)
public Edge<V,E> getEdge(Edge<V,E> e) \{
// Go through all V's adjacent edges and compare Iterator<Edge<V,E>> edges = adjacencies.iterator(); while (edges.hasNext()) \{

Edge<V,E> adjE = edges.next();
if (e.equals(adjE))
return adjE;
\}
return null;

## GraphListDirected

- GraphListDirected/Undirected implement any methods requiring different treatment due to directedness of edges
- addEdge, remove, removeEdge, ...
- We will only look at GraphListDirected in this video because the concepts are similar, and undirected version is slightly more straightforward

```
// in GraphListDirected.java
```

```
// first vertex is source, second is destination
public void addEdge(V vLabel1, V vLabel2, E label) {
    // first get the vertices
    GraphListVertex<V,E> v1 = dict.get(vLabel1);
    GraphListVertex<V,E> v2 = dict.get(vLabel2);
    // create the new edge
    Edge<V,E> e = new Edge<V,E>(v1.label(), v2.label(), label, true);
    // add edge only to source vertex linked list (aka adjacency list)
    v1.addEdge(e);
}
```

```
// in GraphListDirected.java
public V remove(V label) {
    //Get vertex out of map/dictionary
    GraphListVertex<V,E> v = dict.get(label);
    //Iterate over all vertex labels (called the map "keyset")
    Iterator<V> vi = iterator();
    while (vi.hasNext()) {
        //Get next vertex label in iterator
        V v2 = vi.next();
        //Remove all edges to "label"
        //If edge does not exist, removeEdge returns null
        removeEdge(v2,label);
    }
    //Remove vertex from map
    dict.remove(label);
    return v.label();
}
```

```
// in GraphListDirected.java
public E removeEdge(V vLabel1, V vLabel2) {
    //Get vertices out of map
    GraphListVertex<V,E> v1 = dict.get(vLabel1);
    GraphListVertex<V,E> v2 = dict.get(vLabel2);
    //Create a "temporary" edge connecting two vertices
    Edge<V,E> e = new Edge<>(v1.label(), v2.label(), null, true);
    //Remove edge from source vertex linked list
    e = v1.removeEdge(e);
    if (e == null) {
        return null;
    } else {
        return e.label();
    }
}
```


## GraphList: Big Picture

- Maintain an adjacency list of edges at each vertex (no adjacency matrix)
- Keep only outgoing edges for directed graphs
- Space: we only "pay for what we store"
- Vertex lists are as large as there are edges
- Performance: no "direct" way to access edges
- We can quickly find a vertex, but need to scan through its unordered adjacency list


## GraphList Efficiency (assuming $\mathrm{O}(\mathrm{I})$ Map operations)

## For a GraphListDirected<V, E>

- where $|\mathrm{E}|=$ number of edges, and $|\mathrm{V}|=$ number of vertices

| Operation | Big-O |
| :--- | :--- |
| add(V label) | $\mathrm{O}(\mathrm{I})$ |
| remove(V label) | $\mathrm{O}(\|\mathrm{V}\|+\|\mathrm{E}\|)$ |
| addEdge(V v1, V v2) | $\mathrm{O}(\|\mathrm{E}\|)$ |
| getEdge(V v1, V v2) | $\mathrm{O}(\|\mathrm{E}\|)$ |
| removeEdge(V v1, V v2) | $\mathrm{O}(\|\mathrm{E}\|)$ |
|  |  |
| Space Usage | $\mathrm{O}(\|\mathrm{V}\|+\|\mathrm{E}\|)$ |

